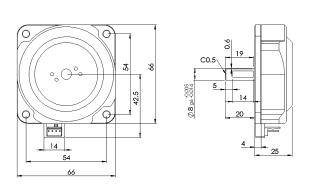
PSM60S-A



Sensorless single-shaft motor for general environment

The minimum size in PSM 60S series.

It is suitable for positioning using a sensor mounted on the device or as an intermittent same action motor with a timer.



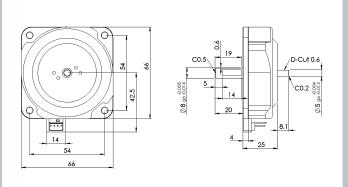
Model Name	Single-shaft motor PSM60S-A
Drive Frequency	40~45 [KHz] Number of rotations
Drive Voltage	130 [Vrms] 180[rpm]
Rated Speed	120 [rpm] 175 0.6[N·m] / 120[rpm]
Maximum Speed	180 [rpm] 125 - 100 -
Rated Torque	0.6 [N·m] 75 - 1.2[N·m] / 15[rpm]
Maximum Torque	1.2 [N·m] 50 + 25 +
Holding Torque	1.2 [N·m] 0 0.25 0.5 0.75 1.0 1.25 [N·m]
Direction & Response	CW、CCW、Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×45 [mm]
Weight	230 [g]
Encoder resolution	Without encoder, single-shaft
Minimum Accuracy	Depends on external sensor

PSM60S-B



Sensorless double-shaft motor for general environment.

It has a sub shaft for directly attaching external sensors made by other companies to the motor. Control using the encoder and tacho generator becomes possible.



Model Name	Double-shaft motor PSM60S-B
Drive Frequency	40~45 [KHz] Number of rotations
Drive Voltage	130 [Vrms] 180[rpm]
Rated Speed	120 [rpm] 175 0.6[N·m] / 120[rpm]
Maximum Speed	180 [rpm] 125 - 100 -
Rated Torque	0.6 [N·m] 75 - 1.2[N·m] / 15[rpm]
Maximum Torque	1.2 [N·m] 50 - 25 - Torque
Holding Torque	1.2 [N·m] 0 0.25 0.5 0.75 1.0 1.25 [N·m]
Direction & Response	CW\CCW\CW\CCW\Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×53 [mm]
Weight	233 [g]
Encoder resolution	Without encoder, double-shaft
Minimum Accuracy	Depends on external sensor

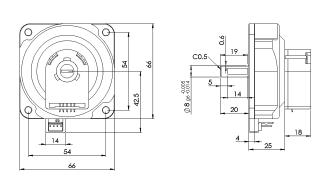
APPEARANCE / FEATURE

PSM60S-E



Motor with 500 p/r encoder for general environment. Equipped with 500 pulse/turn TTL signals output encoder.

Motor position and speed can be controlled with accuracy of \pm 0.18 $^{\circ}$ (Multiplying by 4 times). It is ideal as a motor for transfer equipment using ball screws.



Model Name	Motor with 500 p/r encoder PSM60S-E
Drive Frequency	40~45 [KHz] Number of rotations [rom] A
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm] 175 150 0.6[N·m] / 120[rpm]
Maximum Speed	180 [rpm] 125 100
Rated Torque	0.6 [N·m] 75 1.2[N·m] / 15[rpm]
Maximum Torque	1.2 [N·m] 25
Holding Torque	1.2 [N·m] 0 0.25 0.5 0.75 1.0 1.25 [N·m]
Direction & Response	CW、CCW、Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×63 [mm]
Weight	250 [g]
Encoder resolution	500 [p/r]
Minimum Accuracy	0.18°

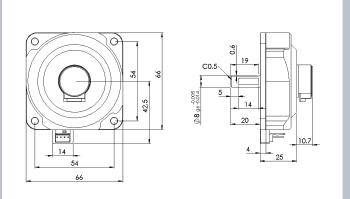
PSM60S-ET



Motor with 1,000 p/r encoder for general environment. Equipped with 1,000 pulse/turn TTL signals output encoder.

Motor position and speed can be controlled with accuracy of \pm 0.09 $^{\circ}$ (Multiplying by 4 times).

It is ideal as a motor for transportation equipment such as high-precision positioning stages.



Model Name	Motor with 1,000 p/r encoder PSM60S-ET
Drive Frequency	40~45 [KHz] Number of rotations from A
Drive Voltage	130 [Vrms]
Rated Speed	120 [rpm] 175 150 0.6[N·m] / 120[rpm]
Maximum Speed	180 [rpm] 125 -
Rated Torque	0.6 [N·m] 75 1.2[N·m] / 15[rpm]
Maximum Torque	1.2 [N·m] 25
Holding Torque	1.2 [N·m] 0 0.25 0.5 0.75 1.0 1.25 N·m
Direction & Response	CW、CCW、Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×56 [mm]
Weight	240 [g]
Encoder resolution	1,000 [p/r]
Minimum Accuracy	0.09°

Motor for general environment

PSM60S SERIES

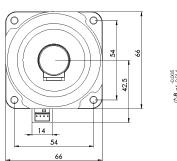
PSM60S-E2T

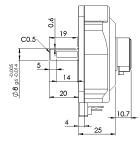


Motor with 2,000 p/r encoder for general environment. Equipped with 2,000 pulse/turn TTL signals output encoder.

Motor position and speed can be controlled with accuracy of \pm 0.045 $^{\circ}$ (Multiplying by 4 times).

It is ideal as a motor for ultra-high precision indexing equipment.





Model Name Motor with 2,000 p/r encoder PSM60S-E2T
Drive Frequency 40~45 [KHz] Number of rotations
Drive Voltage 130 [Vrms]
Rated Speed 120 [rpm] 175 0.6[N·m] / 120[rpm]
Maximum Speed 180 [rpm] 125 - 100 -
Rated Torque 0.6 [N·m] 75 - 1.2[N·m] / 15[rpr
Maximum Torque 1.2 [N⋅m] 50 + 25 +
Holding Torque 1.2 [N·m] 0 0.25 0.5 0.75 1.0 1.25 N·m
Direction & Response CW、CCW、Less than 1 [ms] (No-load)
Temperature Range $-10 \sim +55 [^{\circ}C]$
Life Time 3,000 [Hours]
Size(W×D×H) 66×66×56 [mm]
Weight 240 [g]
Encoder resolution 2,000 [p/r]
Minimum Accuracy 0.045°

Motor for magnetic field environment

PSM60N SERIES

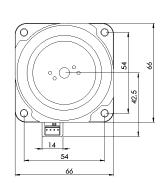
PSM60N-A

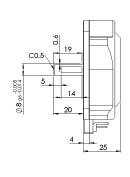


Sensorless single-shaft motor for magnetic field environment.

Applicable to 3 [T] magnetic field environment. Minimum size for PSM 60 N series.

It is ideal as a positioning and transport motor using sensors installed in devices such as MRI and elemental analyzers that are used in high-magnetic field.





Model Name	Single-shaft motor PSM60N-A
Drive Frequency	40~45 [KHz] Number of rotations
Drive Voltage	130 [Vrms] 180[rpm]
Rated Speed	120 [rpm] 175 0.6[N·m] / 120[rpm]
Maximum Speed	180 [rpm] 125 - 100 - 10
Rated Torque	0.6 [N·m] 75 - 1.2[N·m] / 15[rpm]
Maximum Torque	1.2 [N·m] 50 to 25
Holding Torque	1.2 [N·m] 0 0.25 0.5 0.75 1.0 1.25 [N·m]
Direction & Response	CW\CCW\Less than 1 [ms] (No-load)
Temperature Range	-10 ~ +55 [°C]
Life Time	3,000 [Hours]
Size(W×D×H)	66×66×45 [mm]
Weight	230 [g]
Encoder resolution	Without encoder, single-shaft
Minimum Accuracy	Depends on external sensor